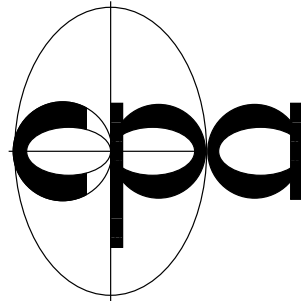


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Linear MHD waves in Cartesian geometry.
Transverse inhomogeneity and mixed properties.

Marcel GOOSSENS

Centre mathematical Plasma Astrophysics, KU Leuven, Belgium



”This is why I love elementary school so much.
The kids really believe everything you tell them”
Principal Seymour Skinner to Mrs. Edna Crabapple
The Simpsons.

- Linear motions superimposed on a static equilibrium state.
- Displace the plasma element from \vec{r} to $\vec{r} + \vec{\xi}$

$$\vec{r} \rightarrow \vec{r} + \vec{\xi}.$$

- $\vec{\xi} = \text{Lagrangian displacement.}$
- Changes in density, pressure and magnetic field.
- Eulerian description / Lagrangian description.
- Linearise MHD equations.

Equations for linear MHD waves

$$\rho' = -\nabla \cdot (\rho_0 \vec{\xi}),$$

$$p' = -\vec{\xi} \cdot \nabla p_0 - \gamma p_0 \nabla \cdot \vec{\xi},$$

$$\vec{B}' = \nabla \times (\vec{\xi} \times \vec{B}_0),$$

$$\rho_0 \frac{\partial^2 \vec{\xi}}{\partial t^2} = -\nabla p' + \frac{1}{\mu} (\nabla \times \vec{B}_0) \times \vec{B}' + \frac{1}{\mu} (\nabla \times \vec{B}') \times \vec{B}_0$$

$$P' = p' + \frac{\vec{B}_0 \cdot \vec{B}'}{\mu}$$

- P' = important quantity for understanding of mixed properties of MHD waves in non-uniform plasmas.
- Solutions of the form

$$f(\vec{r}; t) = \tilde{f}(\vec{r}) \exp(-i\omega t)$$

- $\tilde{f}(\vec{r})$ is the time independent part of any of the perturbed quantities f .

Linear MHD waves in Cartesian geometry

- First step: Uniform plasma of infinite extent.
- Equilibrium quantities

$$\vec{B}_0 = (0, 0, B_z), \quad p_0 = \text{constant}, \quad \rho_0 = \text{constant}.$$

- The coefficients of the partial differential equations in space are constants.
- Solutions in the form of plane waves

$$\tilde{f}(\vec{r}) = \hat{f} \exp(i\vec{k}\cdot\vec{r}) = \hat{f} \exp(i(k_x x + k_y y + k_z z)).$$

- Combine the temporal and spatial factors

$$\begin{aligned} f(\vec{r}; t) &= \tilde{f}(\vec{r}) \exp(-i\omega t) = \hat{f} \exp(i(\vec{k}\cdot\vec{r} - \omega t)) \\ &= \hat{f} \exp(i(k_x x + k_y y + k_z z - \omega t)). \end{aligned}$$

- \hat{f} = constant amplitude of f , $\vec{k} = k_x \vec{1}_x + k_y \vec{1}_y + k_z \vec{1}_z$ = the wave vector.

- \vec{B}_0 defines a preferred direction : $\xi_z = \xi_{\parallel}$, $(\nabla \times \vec{\xi})_z = (\nabla \times \vec{\xi})_{\parallel}$.

ξ_z = component parallel to \vec{B}_0

$\nabla \cdot \vec{\xi} = i \vec{k} \cdot \vec{\xi} = i Y$ = compression

$(\nabla \times \vec{\xi})_z = i (\vec{k} \times \vec{\xi}) \cdot \vec{1}_z = i Z$ = component of vorticity parallel to \vec{B}_0

- $X = k_z \xi_z$, $Y = \vec{k} \cdot \vec{\xi}$, $Z = (\vec{k} \times \vec{\xi}) \cdot \vec{1}_z$

$$\begin{aligned} \omega^2 X - k_z^2 v_s^2 Y &= 0, \\ k^2 v_A^2 X + (\omega^2 - k^2(v_A^2 + v_s^2)) Y &= 0, \\ \bullet \bullet \bullet \bullet \bullet \bullet \bullet & \\ (\omega^2 - \omega_A^2) Z &= 0. \end{aligned}$$

- Two **uncoupled** subsets of equations.
- Two types of solutions.

Classic Alfvén waves

- $\xi_z = 0, Y = 0, Z \neq 0.$

$$\omega^2 = \omega_A^2 = \frac{(\vec{k} \cdot \vec{B}_0)^2}{\mu \rho_0} = k_z^2 v_A^2, \quad v_A^2 = \frac{B_0^2}{\mu \rho_0}$$

- ω_A = local Alfvén frequency.
- **No compression, no parallel displacement; parallel vorticity.**
- Restoring force = Magnetic tension force.
- **No variation of total pressure $P' = 0$**
- Flow of energy along \vec{B} with velocity v_A .
- Extremely an-isotropic.
- **The displacement $\vec{\xi}$ for Alfvén waves .**

$$\vec{\xi}_A = \left(-\frac{k_y}{k_x} \vec{1}_x + \vec{1}_y\right) \xi_y = \left(\vec{1}_x - \frac{k_x}{k_y} \vec{1}_y\right) \xi_x.$$

- Popular choice $k_y = 0$: $\vec{\xi}_A = \xi_y \vec{1}_y$.
- y -independent Alfvén waves are a special case.
- $k_y = 0 \Leftrightarrow m = 0, \quad k_y \neq 0 \Leftrightarrow m \neq 0.$

- Keep $k_y \neq 0$, $k_z \neq 0$ and finite.
- Take $\lim k_x \rightarrow +\infty$ so that $|k_y| \ll |k_x|$, $|k_z| \ll |k_x|$.

$$\frac{|\xi_y|}{|\xi_x|} = \frac{|k_x|}{|k_y|} \gg 1, \quad \vec{\xi}_A \approx \xi_y \vec{1}_y.$$

- $\vec{\xi}$ predominantly in the y -direction and rapidly varying in the x -direction.
- **3 components of vorticity $\nabla \times \vec{\xi}$ are non-zero.**

$$(\nabla \times \vec{\xi})_z = i(k_x \xi_y - k_y \xi_x), \quad (\nabla \times \vec{\xi})_x = -i k_z \xi_y, \quad (\nabla \times \vec{\xi})_y = i k_z \xi_x, \quad \xi_x = -\frac{k_y}{k_x} \xi_y.$$

- Take $\lim k_x \rightarrow +\infty$

$$|(\nabla \times \vec{\xi})_y| \ll |(\nabla \times \vec{\xi})_x| \ll |(\nabla \times \vec{\xi})_z|; \quad \nabla \times \vec{\xi} \approx (\nabla \times \vec{\xi})_z \vec{1}_z.$$

Magneto-sonic slow and fast waves

- $Y \neq 0, \xi_z \neq 0, Z = 0.$
- **Compression, parallel displacement, no parallel vorticity.**
- **Solutions**

$$\omega^2 = \omega_{sl,f}^2 = \frac{k^2(v_S^2 + v_A^2)}{2} \left\{ 1 \pm \left(1 - \frac{4\omega_C^2}{k^2(v_S^2 + v_A^2)} \right)^{1/2} \right\}, \quad \omega_{(B=0)}^2 = k^2 v_S^2$$

- $\omega_C =$ the cusp frequency: $\omega_C^2 = \frac{v_S^2}{v_S^2 + v_A^2} \omega_A^2, \quad v_S^2 = \frac{\gamma p_0}{\rho_0}.$
- "sl" (slow) = the minus sign, "f" (fast) = the plus sign.
- Driven by tension and pressure forces.
- **Variation of total pressure $P' \neq 0$**
- Plasma pressure and magnetic pressure variations are in phase / antiphase.
- **The displacement $\vec{\xi}$ for sl/f magneto-acoustic waves:**

$$\vec{\xi}_{sl,f} = \left(\vec{1}_x + \frac{k_y}{k_x} \vec{1}_y + \frac{\omega_{sl,f}^2 - k^2 v_A^2}{\omega_{sl,f}^2} \frac{k_z}{k_x} \vec{1}_z \right) \xi_x,$$

$$\vec{\xi}_{sl,f} = \left(\frac{\omega_{sl,f}^2}{\omega_{sl,f}^2 - k^2 v_A^2} \frac{k_x}{k_z} \vec{1}_x + \frac{\omega_{sl,f}^2}{\omega_{sl,f}^2 - k^2 v_A^2} \frac{k_y}{k_z} \vec{1}_y + \vec{1}_z \right) \xi_z.$$

- **Popular view: horizontal motion** (ξ_x, ξ_y) **is dominant for fast waves, parallel motion** ξ_z **is dominant for slow waves.**
- **True? Not the general rule!**
- **OK for strong magnetic fields, i.e.** $v_A \gg v_S$

$$\vec{\xi}_f \approx (\vec{1}_x + \frac{k_y}{k_x} \vec{1}_y) \xi_x; \quad \vec{\xi}_{sl} \approx \xi_z \vec{1}_z.$$

- **No parallel vorticity but the horizontal components are non-zero**

$$\nabla \times \vec{\xi} = -i k_z \frac{k^2 v_A^2}{\omega_{sl,f}^2} \xi_x \left(\frac{k_y}{k_x} \vec{1}_x - \vec{1}_y \right).$$

- **Division is clear.**
- **Parallel vorticity $\neq 0$ & compression = 0, $\xi_{\parallel} = 0$: Alfvén waves.**
- **Parallel vorticity = 0 & compression $\neq 0$, $\xi_{\parallel} \neq 0$: M-A waves.**
- **No mixing of properties.**
- **Pressureless plasma $v_S^2 = 0$: $\omega_{sl}^2 = 0$, $\omega_f^2 = k^2 v_A^2$, $\xi_z = 0$.**
- **No slow waves and the fast magneto-sonic waves have no parallel motions.**

- Introduce non-uniformity.

Surface Alfvén waves

- Aim = study **surface Alfvén waves on a density discontinuity**
- Long way: study **linear MHD waves in planar geometry**

Linear MHD waves in planar geometry

- Cartesian coordinates x, y, z .
- Equilibrium model: Planar plasma in static equilibrium.
- **Equilibrium quantities** $\vec{B}_0 = (0, 0, B_0(x))$, $p_0(x)$ and $\rho_0(x)$.
- Two preferred directions: $\vec{1}_x, \vec{1}_z$.

-

$$\nabla \times \vec{B}_0 = -\frac{dB_0}{dx}\vec{1}_y, \quad (\nabla \times \vec{B}_0) \times \vec{B}_0 = -\frac{d}{dx}\left(\frac{B_0^2}{2\mu}\right)\vec{1}_x$$

- Force balance equation

$$\frac{d}{dx}\left(p_0 + \frac{B_0^2}{2\mu}\right) = 0$$

-

- Fourier analyze with respect to the ignorable coordinates y, z
-

$$\exp(i(k_y y + k_z z)), \quad k^2 = k_y^2 + k_z^2.$$

- Remember $\exp(-i\omega t)$
- Perturbed quantities $\vec{\xi}, f'$ are proportional to

$$\exp(i(k_y y + k_z z - \omega t))$$

-

$$\begin{aligned} f'(x, y, z; t) &= f'_*(x) \exp(i(k_y y + k_z z - \omega t)) \\ \vec{\xi}(x, y, z, t) &= \vec{\xi}_*(x) \exp(i(k_y y + k_z z - \omega t)) \end{aligned}$$

- In what follows drop underscript $*$ and drop factor $\exp(i(k_y y + k_z z - \omega t))$
-

$$\omega_A^2 = \frac{(k_z B_0(x))^2}{\mu \rho_0} = k_z^2 v_A^2(x)$$

- $\omega_A(x)$ = local Alfvén frequency; $v_A(x)$ = local Alfvén velocity. In a non-uniform plasma $\omega_A(x)$ defines the Alfvén continuum.

-

$$[\min \omega_A, \max \omega_A]$$

-

$$\omega_C^2 = \omega_A^2 \frac{v_S^2}{v_S^2 + v_A^2}$$

- $\omega_C(x)$ = local cusp frequency; $v_S(x)$ = local speed of sound. In a non-uniform plasma $\omega_C(x)$ defines the cusp or slow continuum.

-

$$[\min \omega_C, \max \omega_C]$$

- Aim = two 1st order ODE for ξ_x and P'
- Express the remaining variables in terms of ξ_x and P'

- Classic ODEs for ξ_x and P'

$$D \frac{d\xi_x}{dx} = -C_2 P',$$

$$\frac{dP'}{dx} = \rho(\omega^2 - \omega_A^2) \xi_x.$$

$$D = \rho_0(v_S^2 + v_A^2)(\omega^2 - \omega_A^2)(\omega^2 - \omega_C^2),$$

$$C_2 = \omega^4 - (v_S^2 + v_A^2)(\omega^2 - \omega_C^2)(k_y^2 + k_z^2),$$

- Equations for ξ_y , ξ_z , and $\nabla \cdot \vec{\xi}$

$$\rho(\omega^2 - \omega_A^2) \xi_y = ik_y P',$$

$$\rho_0(\omega^2 - \omega_C^2) \xi_z = ik_z \frac{v_S^2}{v_S^2 + v_A^2} P'$$

$$\nabla \cdot \vec{\xi} = \frac{-\omega^2 P'}{\rho_0 (v_S^2 + v_A^2) (\omega^2 - \omega_C^2)}$$

- Components of $(\nabla \times \vec{\xi})$

$$\begin{aligned}
 (\nabla \times \vec{\xi}) \cdot \vec{1}_x &= k_z k_y \frac{v_A^2}{v_S^2 + v_A^2} \frac{\omega^2}{\rho_0(\omega^2 - \omega_A^2)(\omega^2 - \omega_C^2)} P' \\
 (\nabla \times \vec{\xi}) \cdot \vec{1}_y &= -ik_z \frac{d}{dx} \left\{ \frac{v_S^2}{v_A^2 + v_S^2} \frac{1}{\rho_0(\omega^2 - \omega_C^2)} \right\} P' \\
 &\quad + ik_z \frac{\omega^2}{\rho_0(\omega^2 - \omega_A^2)(\omega^2 - \omega_C^2)} \frac{v_A^2}{v_A^2 + v_S^2} \frac{dP'}{dx} \\
 (\nabla \times \vec{\xi}) \cdot \vec{1}_z &= -ik_y P' \frac{1}{\{\rho_0(\omega^2 - \omega_A^2)\}^2} \frac{d}{dx} \left\{ \rho_0(\omega^2 - \omega_A^2) \right\}
 \end{aligned}$$

- Note v_S^2 , v_A^2 , ω_A^2 , and ω_C^2 are functions of position.
- The equations are coupled .
- The coupling functions C_A and C_S
-

$$C_A = ik_y P', \quad C_S = ik_z \frac{v_S^2}{v_S^2 + v_A^2} P'$$

- **General rule: all wave variables are non-zero.**
- No pure fast magneto-sonic waves and no pure Alfvén waves.
- **Very different from infinite uniform plasma.**
- A. Hasegawa and C. Uberoi, 1982 "The Alfvén wave".
- The basic characteristic of the ideal Alfvén wave is that the total pressure in the fluid remains constant during the passage of the wave as a consequence of the incompressibility condition. **For inhomogeneous medium, however, the total pressure, in general, couples with the dynamics of the motion, and the assumption of neglect of pressure perturbations becomes invalid.**
- **P' couples the equations.**
- The MHD waves have mixed properties.
- Always mixed properties except for $k_y = 0$: $k_y = 0 \ C_A = 0$.
- Equation for ξ_y is decoupled

$$\rho(\omega^2 - \omega_A^2)\xi_y = 0$$

- Pure Alfvén waves for $k_y = 0$ in a non-uniform planar plasma .
- $k_y = 0$: y-invariant Alfvén waves and y-invariant magneto-sonic waves.

Linear incompressible MHD waves in planar geometry

- Incompressibility means that the speed of sound is far faster than any other velocity in the system. Mathematically this means

-

$$\nabla \cdot \vec{\xi} = 0, \quad \lim v_S \rightarrow \infty$$

- Characteristic frequencies

$$\omega_C = \omega_A$$

- The slow and Alfvén continua coincide. Note that the Alfvén continuum has its dominant singularity in ξ_y while for the slow continuum the dominant singularity is in ξ_z . Both singularities are present.
- P' is a dependent unknown variable that cannot be computed by using expressions for the components of $\vec{\xi}$.

- Equations for incompressible motions on a non-uniform Cartesian 1-D equilibrium

$$\rho(\omega^2 - \omega_A^2) \frac{d}{dx} \left\{ \frac{1}{\rho(\omega^2 - \omega_A^2)} \frac{dP'}{dx} \right\} = k^2 P'$$

$$\rho(\omega^2 - \omega_A^2) \xi_x = \frac{dP'}{dx}$$

$$\rho(\omega^2 - \omega_A^2) \xi_y = ik_y P'$$

$$\rho_0(\omega^2 - \omega_A^2) \xi_z = ik_z P'$$

- Components of $(\nabla \times \vec{\xi})$

$$(\nabla \times \vec{\xi}) \cdot \vec{1}_x = 0$$

$$(\nabla \times \vec{\xi}) \cdot \vec{1}_y = ik_z P' \frac{1}{\{\rho_0(\omega^2 - \omega_A^2)\}^2} \frac{d}{dx} \{\rho_0(\omega^2 - \omega_A^2)\}$$

$$(\nabla \times \vec{\xi}) \cdot \vec{1}_z = -ik_y P' \frac{1}{\{\rho_0(\omega^2 - \omega_A^2)\}^2} \frac{d}{dx} \{\rho_0(\omega^2 - \omega_A^2)\}$$

- All wave variables, with the exception of compression and the x -component of $\nabla \times \vec{\xi}$, are non-zero in a non-uniform plasma. The 3 components of the Lagrangian displacement are non-zero.

$$k^2 = k_y^2 + k_z^2$$

A piece-wise constant density planar geometry

$$\rho(x) = \begin{cases} \rho_i & \text{if } x \leq 0, \\ \rho_e & \text{if } x > 0. \end{cases}$$

- Alfvén continuum is removed and replaced by **2 points**: $\omega_{A,i}, \omega_{A,e}$
- 2nd order ODE for P'

$$\frac{d^2 P'}{dx^2} = k^2 P'$$

- Solutions finite at $\pm\infty$

$$P'_i(x) = A_1 \exp(+kx), \quad \xi_i(x) = A_1 \frac{k}{\rho_i(\omega^2 - \omega_{Ai}^2)} \exp(+kx)$$

$$P'_e(x) = A_2 \exp(-kx), \quad \xi_e(x) = A_2 \frac{-k}{\rho_e(\omega^2 - \omega_{Ae}^2)} \exp(-kx)$$

- Continuity of P' and ξ_x at $x = 0$

$$P'_i(0) = P'_e(0), \quad \xi_i(0) = \xi_e(0)$$

results in

$$A_1 = A_2 = A$$

and the dispersion relation

$$\rho_e(\omega^2 - \omega_{Ae}^2) + \rho_i(\omega^2 - \omega_{Ai}^2) = 0$$

- The dispersion relation can be solved for frequency ω in terms of k_z . This situation corresponds to standing waves with prescribed k_z and a corresponding solution for ω :

$$\omega^2 = \omega_k^2 = \frac{\rho_i \omega_{Ai}^2 + \rho_e \omega_{Ae}^2}{\rho_i + \rho_e} = k_z^2 v_k^2$$

- Conversely ω can be prescribed and the dispersion relation can be solved for k_z . This corresponds to propagating waves. The solution is :

$$k_z^2 = \frac{\omega^2}{v_k^2}$$

v_k is the kink speed. It is defined as

$$v_k^2 = \frac{\rho_i \omega_{Ai}^2 + \rho_e \omega_{Ae}^2}{\rho_i + \rho_e}.$$

For constant magnetic field $B_{zi} = B_{ze}$

$$v_k^2 = \frac{2}{\rho_i + \rho_e} \frac{B_z^2}{\mu}$$

- $\xi_x(x), \xi_y(x), \xi_z(x), P'(x)$ depend on x .
- k defines a length scale $k = 1/R$.
-

$$\exp(\pm(x/R)), \quad x < 0 : +, \quad x > 0 : - \quad R = 1/k$$

- Use constant C

$$C = \frac{A}{(k_z R)^2 \frac{B_z^2}{\mu} \frac{\rho_i - \rho_e}{\rho_i + \rho_e}}$$

- The solutions

$$\frac{P'_i(x)}{(B^2/\mu)} = C (k_z R)^2 \frac{\rho_i - \rho_e}{\rho_i + \rho_e} \exp(x/R),$$

$$\frac{\xi_{x,i}(x)}{R} = C \exp(x/R)$$

$$\frac{\xi_{y,i}(x)}{R} = i C \alpha_y \exp(x/R)$$

$$\frac{\xi_{z,i}(x)}{R} = i C \alpha_z \exp(x/R)$$

$$\frac{P'_e(x)}{(B^2/\mu)} = C (k_z R)^2 \frac{\rho_i - \rho_e}{\rho_i + \rho_e} \exp(-x/R),$$

$$\frac{\xi_{x,e}(x)}{R} = C \exp(-x/R)$$

$$\frac{\xi_{y,e}(x)}{R} = -i C \alpha_y \exp(-x/R)$$

$$\frac{\xi_{z,e}(x)}{R} = -i C \alpha_z \exp(-x/R)$$

$$\alpha_y = \frac{k_y}{k}, \quad \alpha_z = \frac{k_z}{k}, \quad \frac{\xi_y}{\xi_z} = \frac{k_y}{k_z}$$

- ξ_y, ξ_z are discontinuous at $x = 0$ due to change of sign of $\omega^2 - \omega_A^2$.

$$\xi_{y,e}(0) = -\xi_{y,i}(0), \quad \xi_{z,e}(0) = -\xi_{z,i}(0)$$

- Strong counterstreaming motions in the y - and z - directions. Possible cause of KH-instabilities.
- This effect is enhanced when the true discontinuity is replaced with a continuous variation.
- Strong shear at $x = 0$
- Vorticity is present at $x = 0$ due to discontinuity in ξ_y and ξ_z .

$$(\nabla \times \vec{\xi}) \cdot \vec{1}_x = 0$$

$$(\nabla \times \vec{\xi}) \cdot \vec{1}_y = -2k_z P' \frac{\rho_i + \rho_e}{\rho_e \rho_i} \frac{1}{\omega_{A,e}^2 - \omega_{A,i}^2} \delta(x)$$

$$(\nabla \times \vec{\xi}) \cdot \vec{1}_z = 2k_y P' \frac{\rho_i + \rho_e}{\rho_e \rho_i} \frac{1}{\omega_{A,e}^2 - \omega_{A,i}^2} \delta(x)$$

Resonant damping

- The true discontinuity at the surface $x = 0$ is replaced by a continuous variation from ρ_i to ρ_e in an intermediate layer of thickness l $[-l/2 \ l/2]$.
- The characteristic frequencies $\omega_A^2(x) = \omega_C^2(x)$ vary with position x and define the continuous spectrum of resonant Alfvén (slow) waves. Here the two continua coincide.

$$\text{Alfvén continuous spectrum} = [\min \omega_A(x), \max \omega_A(x)]$$

- Take density to be a monotonically decreasing function in the non-uniform layer so that

$$\min \omega_A(x) = \omega_{A,i}, \quad \max \omega_A(x) = \omega_{A,e}$$

Obviously

$$\omega_{A,i} < \omega_k < \omega_{A,e}$$

so the surface Alfvén / slow wave is resonantly damped.

- **No long wave length (thin tube) approximation!**
- Adopt the thin boundary approximation and use the jump condition for incompressible motions:

$$[P'] = 0, \quad [\xi_x] = -i\pi \frac{1}{\rho(x_A) |\Delta|} (k_y^2 + k_z^2) P' = -i\pi \frac{1}{\rho(x_A) |\Delta|} k^2 P'$$

- **Role of P'** Hollweg and Yang 1988, JGR, 93, 93, 5423 - 5436 **Resonance absorption can occur in any situation where total pressure fluctuations are imparted to field lines satisfying the Alfvén and cusp resonances conditions.**
- **Jump in flux of energy across resonant position is proportional to $|P'|^2$.**
- x_A is the position of the resonance where $\omega_k = \omega_A(x_A)$. In the thin boundary approximation $x_A = 0$. The quantity Δ is

$$\Delta = \frac{d}{dx} \{ \omega^2 - \omega_A^2 \} |_{x_A}$$

- The condition on ξ_x is then

$$1 + F - iG = 0$$

with

$$F = \frac{\rho_e(\omega^2 - \omega_{A,e}^2)}{\rho_i(\omega^2 - \omega_{A,i}^2)}, \quad G = \pi \frac{\rho_e(\omega^2 - \omega_{A,e}^2)}{\rho(x_A) |\Delta|} k$$

- The term $-iG$ contains the effect of the resonant damping. When we put $G = 0$ we recover the dispersion relation for the true discontinuity. Its solution is $\omega = \omega_R = \omega_k$.
- Rewrite the dispersion relation $1 + F - iG = 0$ as

$$\omega^2 - k_z^2 v_k^2 = \frac{1}{\rho_i + \rho_e} \frac{i\pi k}{\rho(x_A) |\Delta|} \rho_i(\omega^2 - \omega_{A,i}^2) \rho_e(\omega^2 - \omega_{A,e}^2)$$

- Because of resonant damping the frequency is complex.

$$\omega = \omega_R + i\gamma$$

- The period and the damping time τ_D are

$$\text{Period} = \frac{2\pi}{\omega_R}, \quad \tau_D = \frac{1}{|\gamma|}$$

- **Weak damping:** use a perturbation method. Neglect the effect of resonant damping on the real part of the frequency so that $\omega_R \approx \omega_k$. Also neglect terms of second order in γ/ω_R . Hence

$$\omega_R \approx \omega_k = \omega_A(x_A), \quad \omega^2 \approx \omega_R^2 + 2i\omega_R \gamma$$

- Find then

$$\frac{\gamma}{\omega_R} \approx \frac{-\pi}{2\omega_k^2} \frac{\rho_i^2 \rho_e^2}{(\rho_i + \rho_e)^3} \frac{(\omega_{A,i}^2 - \omega_{A,e}^2)^2}{\rho(x_A) |\Delta|} k$$

- Take $k = 1/R$

$$\frac{\gamma}{\omega_R} \approx \frac{-\pi}{2\omega_k^2} \frac{\rho_i^2 \rho_e^2}{(\rho_i + \rho_e)^3} \frac{(\omega_{A,i}^2 - \omega_{A,e}^2)^2}{\rho(x_A) |\Delta|} \frac{1}{R}$$

This is exactly **Equation 77 of GHS92** when this equation is corrected for a typo and $|m| = 1$.

- Now take equal and constant magnetic fields $B_1 = B_2 = B$
- Straightforward calculation leads to

$$\gamma = -\frac{\pi}{2R} \frac{\rho_A |\omega_k|^3 (\rho_2 - \rho_1)^2}{|\Delta| (\rho_1 + \rho_2)^3}.$$

This is exactly **Equation 56 of Ruderman and Roberts, 2002**

When $B_0 = \text{constant}$ it follows that

$$\rho_0(x_A) |\Delta| = \omega_A^2(x_A) \left| \frac{d\rho_0}{dx} \right|_{x_A} = \omega_k^2 \left| \frac{d\rho_0}{dx} \right|_{x_A}$$

- Hence

$$\frac{\gamma}{\omega_R} = -\frac{\pi}{8} \frac{(\rho_i - \rho_e)^2}{\rho_i + \rho_e} k \left| \frac{d\rho(x)}{dx} \right|_{x_A}$$

Replace k with $k = 1/R$ then

$$\frac{\gamma}{\omega_R} = -\frac{\pi}{8} \frac{(\rho_i - \rho_e)^2}{\rho_i + \rho_e} \frac{1}{R} \left| \frac{d\rho(x)}{dx} \right|_{x_A}$$

- Compare this expression for γ/ω_R with those derived in Goossens et al. 2009. See their equations 31 for a pressureless compressible cylindrical plasma and equation 53 for an incompressible cylindrical plasma. Equations 31 and 53 are derived in the long wave length limit ($k_z R \ll 1$). Equation 31 is identical to the equation derived here. The same applies to equation 53 when we drop the quadratic terms in $k_z R$. **This is a remarkable result. Cylindrical or planar geometry does not make a difference in the long wave length limit.**

- The damping time τ_D

$$\frac{\tau_D}{\text{Period}} = \frac{4}{\pi^2} \frac{\rho_i + \rho_e}{(\rho_i - \rho_e)^2} \frac{1}{k} \left| \frac{d\rho(x)}{dx} \right|_{x_A}$$

- Assume that density $\rho_0(x)$ varies from ρ_i at $x = -l/2$ to ρ_e at $x = +l/2$ with steepness α so that

$$\frac{d\rho(x)}{dx} = -\alpha \frac{\rho_i - \rho_e}{l}$$

For a linear profile $\alpha = 1$, for a sinusoidal profile $\alpha = \pi/2$.

- Damping decrement $\frac{\gamma}{\omega_R}$

$$\frac{\gamma}{\omega_R} = -\frac{\pi}{8} \frac{(\rho_i - \rho_e)}{\rho_i + \rho_e} \frac{kl}{\alpha} = -\frac{\pi}{8} \frac{(\rho_i - \rho_e)}{\rho_i + \rho_e} \frac{l/R}{\alpha}$$

- The damping time τ_D

$$\frac{\tau_D}{\text{Period}} = \frac{4}{\pi^2} \frac{\rho_i + \rho_e}{\rho_i - \rho_e} \frac{\alpha}{kl} = \frac{4}{\pi^2} \frac{\rho_i + \rho_e}{\rho_i - \rho_e} \frac{\alpha}{l/R}$$

- The expressions for γ/ω_R and τ_D/Period agree with the corresponding expressions listed in Goossens et al. 2009 for a cylindrical plasma in the thin tube approximation.

- Go back to ξ_y, ξ_z and components of $(\nabla \times \vec{\xi})$

$$\xi_y = ik_y P' \frac{1}{\rho_0(\omega^2 - \omega_A^2)}$$

$$\xi_z = ik_z P' \frac{1}{\rho_0(\omega^2 - \omega_A^2)}$$

$$(\nabla \times \vec{\xi}) \cdot \vec{1}_y = ik_z P' \frac{1}{\{\rho_0(\omega^2 - \omega_A^2)\}^2} \frac{d}{dx} \{\rho_0(\omega^2 - \omega_A^2)\}$$

$$(\nabla \times \vec{\xi}) \cdot \vec{1}_z = -ik_y P' \frac{1}{\{\rho_0(\omega^2 - \omega_A^2)\}^2} \frac{d}{dx} \{\rho_0(\omega^2 - \omega_A^2)\}$$

- Recall that for MHD waves (weakly) resonantly damped in the Alfvén continuum

$$\omega = \omega_R + i\gamma, \quad \omega_R \approx \omega_A(x_A), \quad \gamma \ll \omega_R$$

- The values of ξ_y, ξ_z are not infinite but very large in absolute value with opposite values of their real parts across the ideal resonant point $x = x_A$.
- **KH-instabilities are difficult to avoid.**

- **Propagating waves.** Now the frequency is given and the dispersion relation determines the wave number k_z .
- Follow and Terradas, Goossens and Verth 2010 (TGV 2010 , A&A, 524, A23) in case of a cylindrical plasma with a straight field.
- No need to use the long wave limit or the thin tube approximation.
- The wave number k_z is complex

$$k_z = k_{z,R} + ik_{z,I}$$

- **The wave length λ and the damping length L_D are**

$$\lambda = \frac{2\pi}{k_{z,R}}, \quad L_D = \frac{1}{|k_{z,I}|}$$

- Use a perturbation method. Neglect the effect of resonant damping on the real part of the wave number so that

$$k_{z,R}^2 \approx \frac{\omega^2}{v_k^2}$$

- The result for the damping length L_D

$$\frac{L_D}{\lambda} = \frac{4}{\pi^2} \frac{\rho_i + \rho_e}{(\rho_i - \rho_e)^2} \frac{1}{k_0} \left| \frac{d\rho(x)}{dx} \right|_{x_A}$$

-

$$k_0 = \sqrt{k_y^2 + k_{z,R}^2}$$

- As before replace the derivative of equilibrium density with

$$\frac{d\rho(x)}{dx} = -\alpha \frac{\rho_i - \rho_e}{l}$$

and arrive at

$$\frac{L_D}{\lambda} = \frac{4}{\pi^2} \frac{\rho_i + \rho_e}{\rho_i - \rho_e} \frac{\alpha}{k_0 l}$$

Conclusions & Comments

- Linear MHD : No interaction of MHD waves.
- Given wave is defined in the whole space.
- Non-uniformity across magnetic field is fundamental.
- It generates MHD waves with mixed properties.
- Pure Alfvén waves and pure magneto-acoustic waves ???
- Non-zero pressure variations & non-zero horizontal and parallel vorticity.
- Properties of given wave depend on properties of background.
- Resonant absorption in Alfvén continuum. Total pressure perturbation is non-zero.
- \approx Alfvén wave = Alfvénic wave .
- Mixed properties = general phenomenon. It does not depend on geometry. Non-uniformity across magnetic field is key.