Magnetic field from NSO Synoptic Program

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GONG and SOLIS





Bird's-eye view of installation of telescope mount

panels (~2.8%)



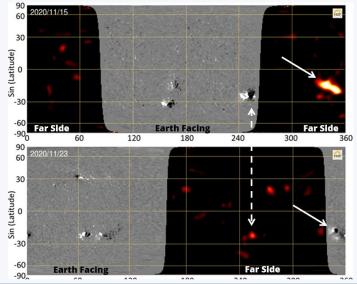




GONG: Helioseismology and Magnetic Fields

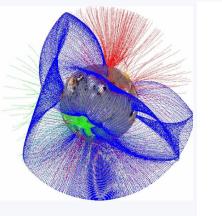
Data for Research and SW Forecast

- <u>Helioseismology:</u> Plasma flows inside the Sun (dynamo, cycle prediction, far-side imaging etc)
- <u>Magnetic fields:</u> LOS photosphere, 3D structure and evolution, flare & CME initiation, irradiance, modeling of solar wind, geomagnetic disturbances etc

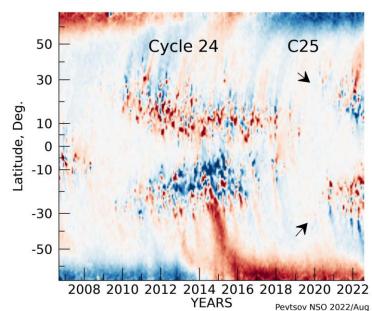


Full disk magnetic, Doppler, and H-alpha data





Modeling of coronal magnetic fields

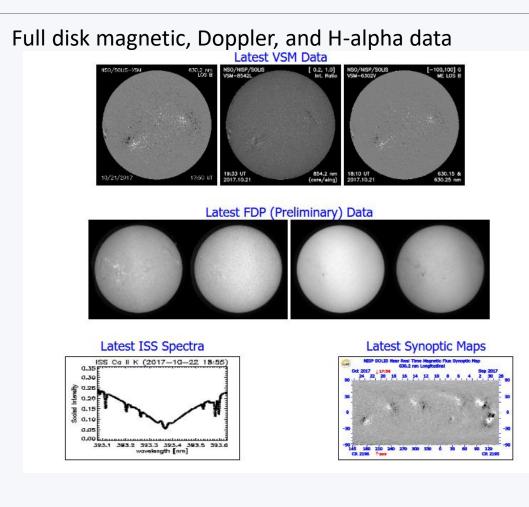


NSO

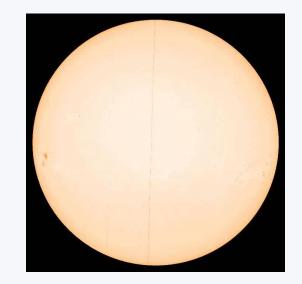




SOLIS: Vector Polarimetry, Imaging, and Sun-as-a-star



- Evolution and 3D orientation of magnetic fields on the Sun
- Physics of solar phenomena (e.g. solar flares, sunspots)
- Solar-stellar research



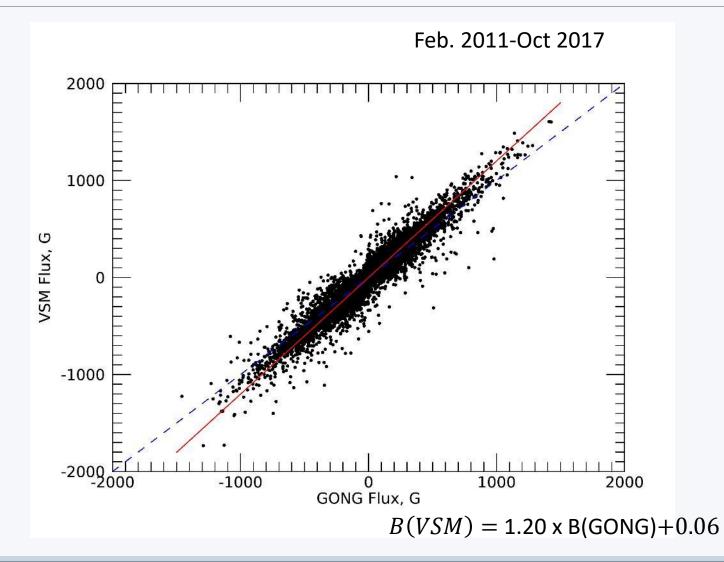
Beck et al. solar atmosphere in 3D







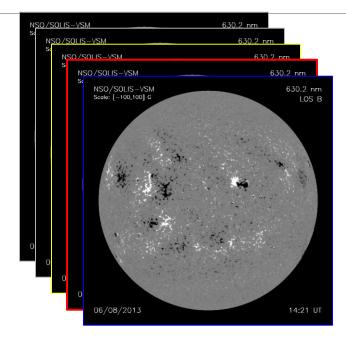
GONG-SOLIS comparison





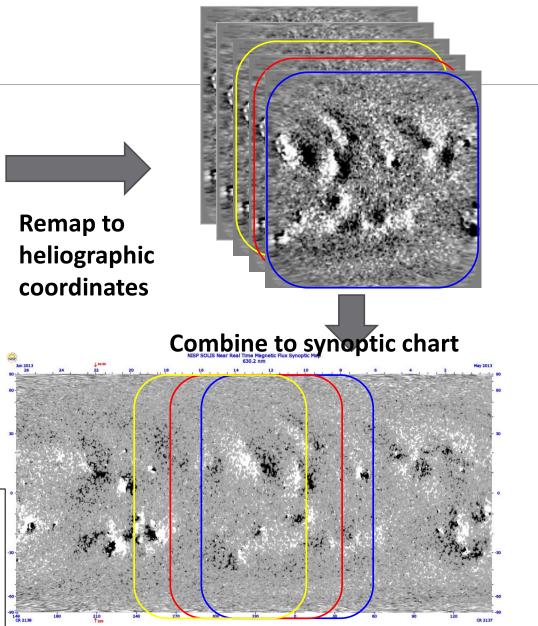






Full disk daily observations in sky-coordinates.

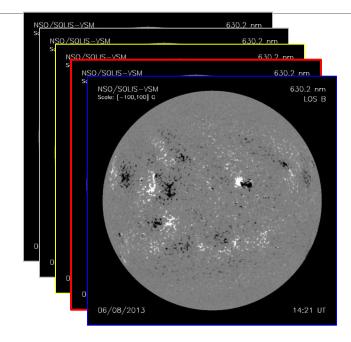
NSO-method uses full disk images weighted by $\cos^4(\lambda)$ function and latitude-dependent "blending" of observed pixels smoothed by a running Gaussian function





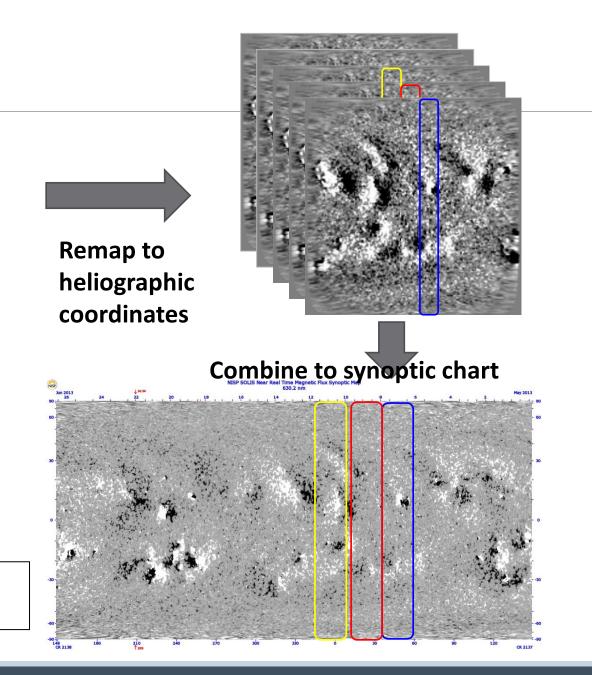






Full disk daily observations in sky-coordinates.

HMI-method uses 2-degree strips at the central meridian







Traditional maps:

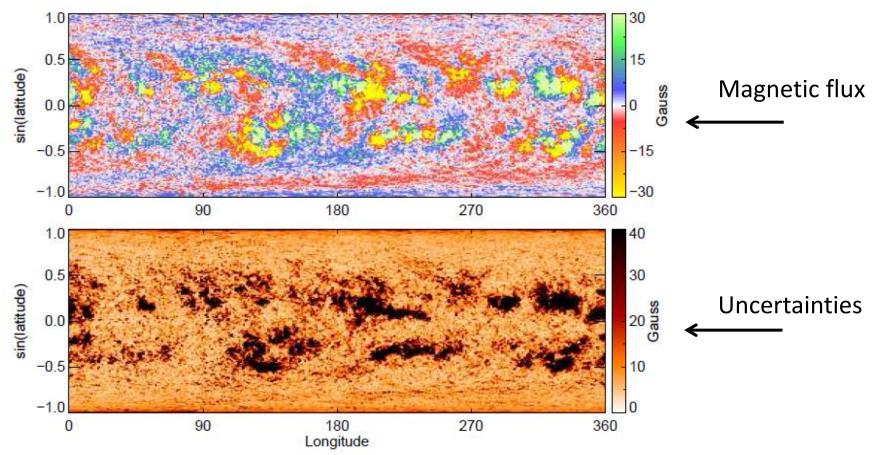
- Pseudo-radial magnetic field: $B_{r-p} \sim B_{LOS}/\cos(r/R)$
- Pole fill (cubic polynomial, for review, see Sun et al: 2011, Solar Physics, 270, 9: doi:10.1007/s11207-011-9751-4).
- No uncertainties in B_{r-p}

More recent data products:

- Synoptic maps of uncertainties
- Vector field (3 components)
- Composite maps (photospheric B_r)
- Pseudo-radial (chromospheric) B_r maps

I. Synoptic maps of uncertainties

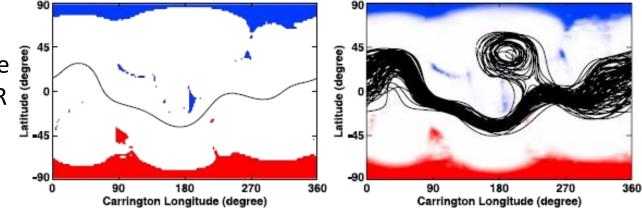




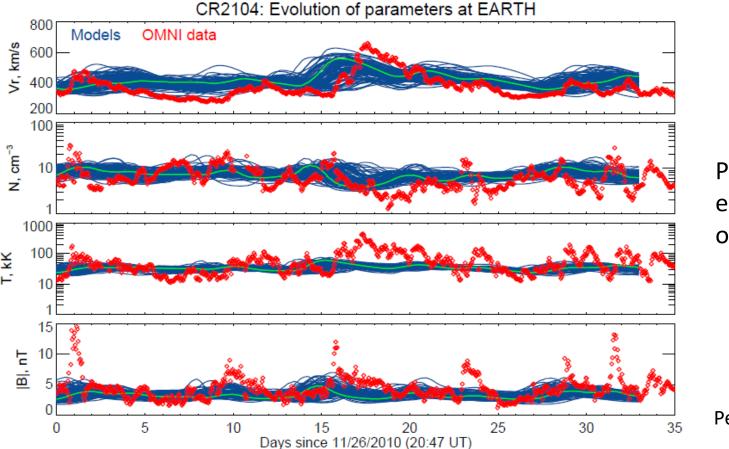
NSO: SOLIS/VSM and HMI (2010-2015)

Bertello et al (2014)

PFSS neutral line (thin black lines) and positive/negative open field footpoints (red/blue pixels) are shown for CR 2104.



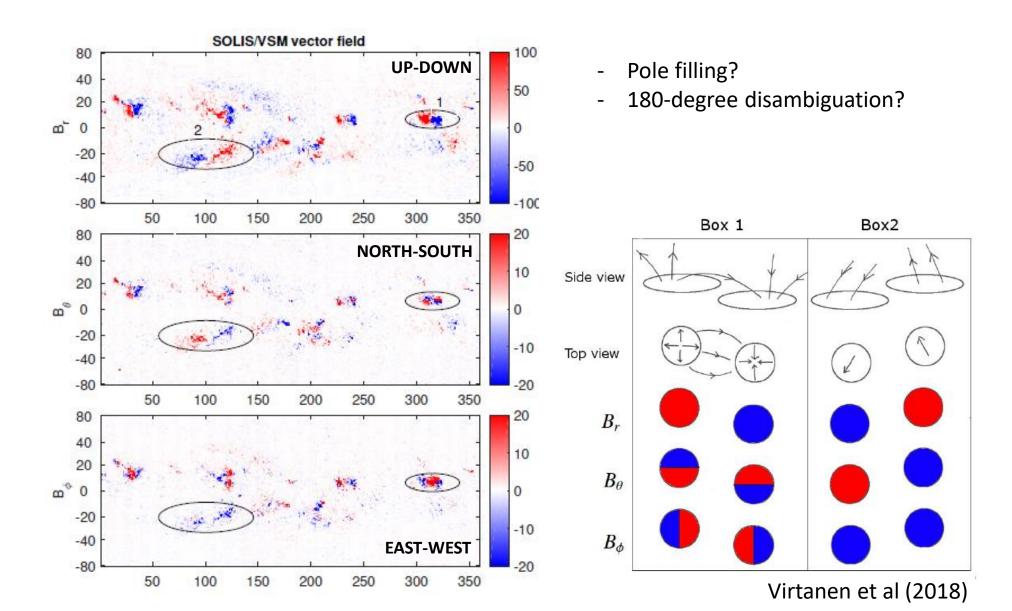
Bertello et al (2014)



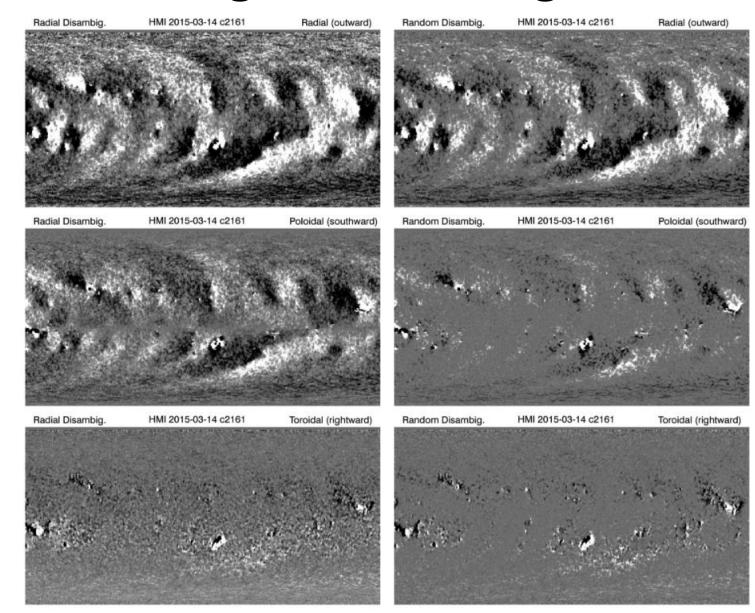
Period of lower sunspot activity: Blue – ensemble modeling, red – in situ observations.

Pevtsov et al (2015)

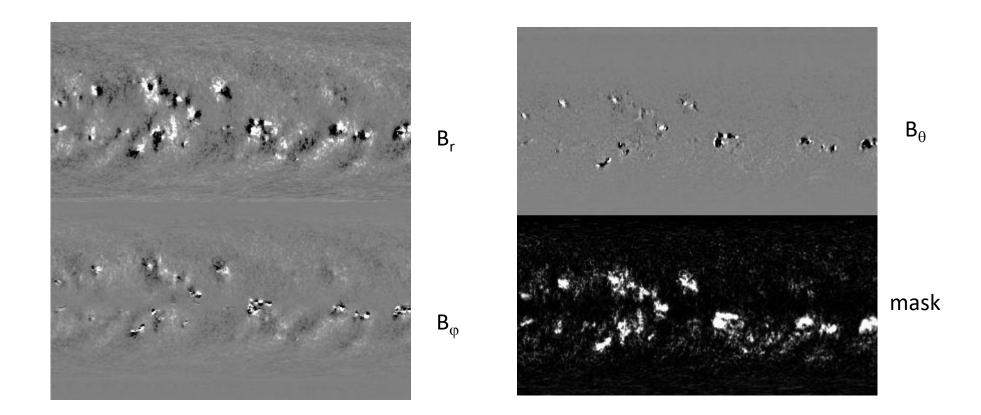
II. Vector Field Synoptic Maps



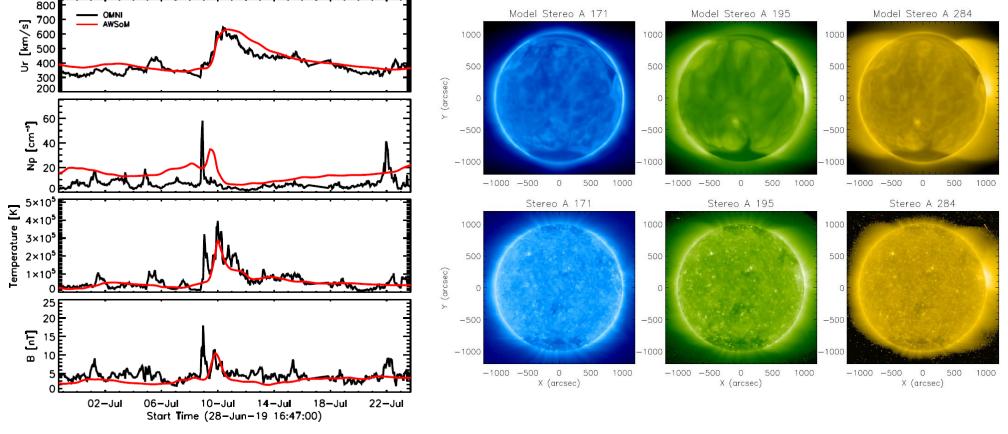
180-degree disambiguation



HMI vector synoptic maps by NSO

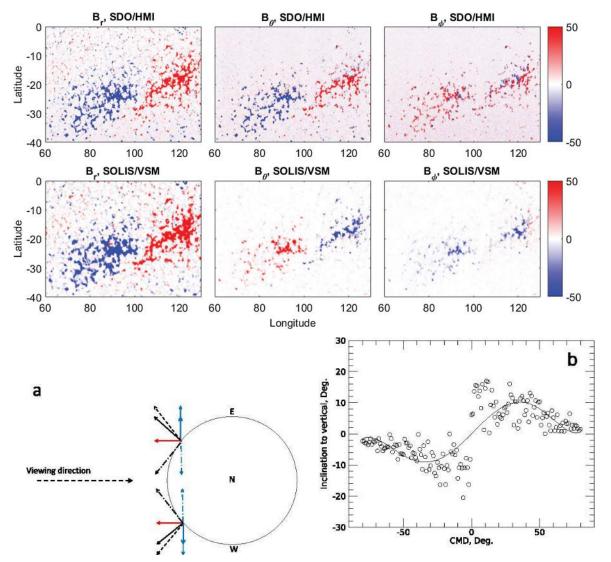


MHD simulations using vector data as input



Tong Shi et al (2021)

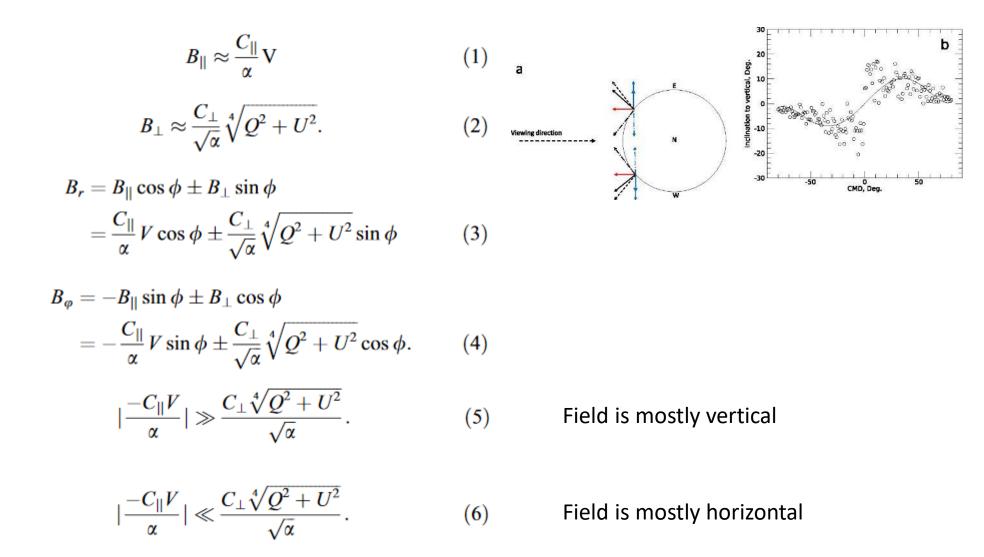
Vector Field open questions



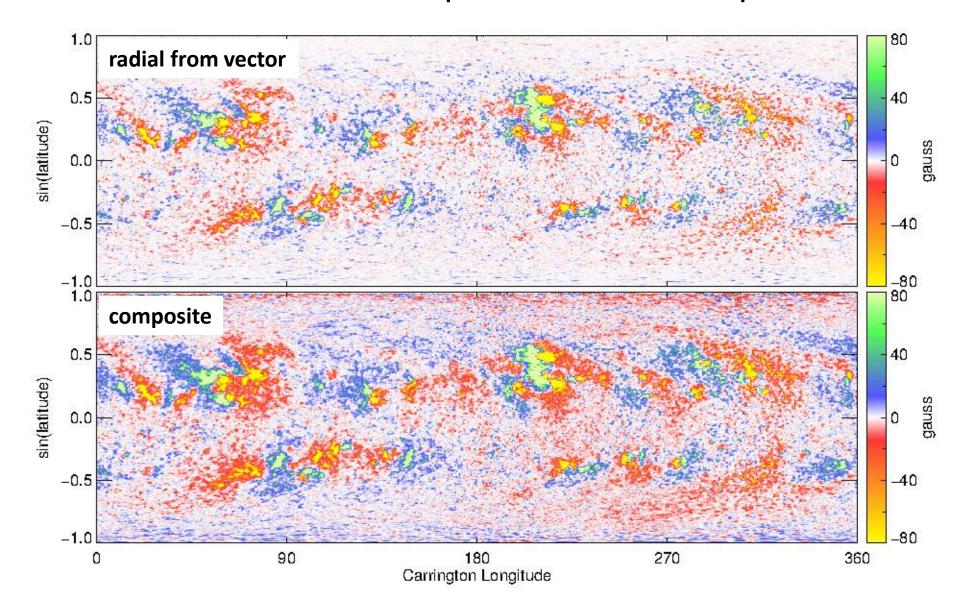
- Difference in noise?
- Fill factor?

Pevtsov et al, 2021, https://doi.org/10.1051/swsc/2021003

Vector Field open questions

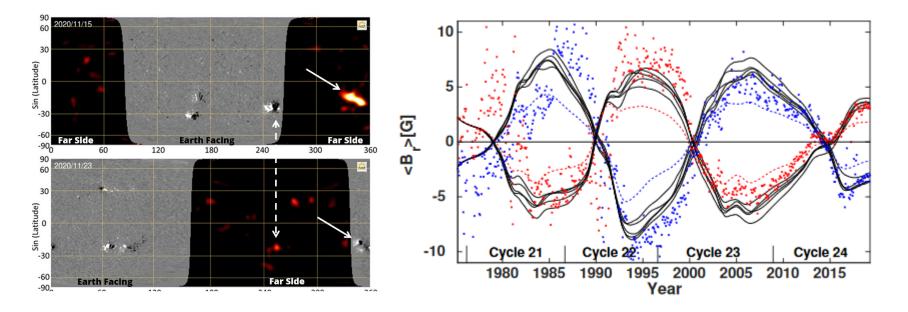


III. Composite (B_r + pseudo-B_r)maps



Synoptic maps shortcomings

- Polar field is not well represented (solutions: pole filling, using surface flux transport/SFT to fill poles), ADAPT model
- Missing flux (far side): SFT



Average strength of polar fields above 60° and below -60° latitude. Dashed – only observed active regions are included. Solid black lines five realizations including additional far-side active regions with a lifetime limit of four days. Red and blue crosses - observed polar field.

Virtanen et al: 2021, A&A, doi: <u>10.1051/0004-6361/202140656</u>

Summary

- Synoptic maps provide boundary conditions for modern modeling of solar corona, solar wind and the heliospheric magnetic field.
- Traditional maps are based on B-los magnetograms, but new data products are now available: (synoptic maps of) uncertainties, vector field, composite, and pseudo-radial chromospheric field.
- Pole filling for vector (and chromospheric) fields and disambiguation are open issues
- Vector data may have some limitations due to difference in noise between B-los and B-trans.